

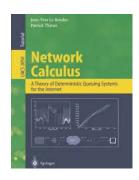
An Introduction to Network Calculus

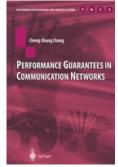
Jean-Yves Le Boudec 2019 April 5

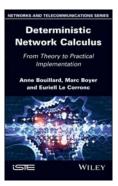
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What is Network Calculus?







A theory and tools to compute bounds on queuing delays, buffers, burstiness of flows, etc.



R Cruz, CS Chang, JY Le Boudec, P Thiran, ...

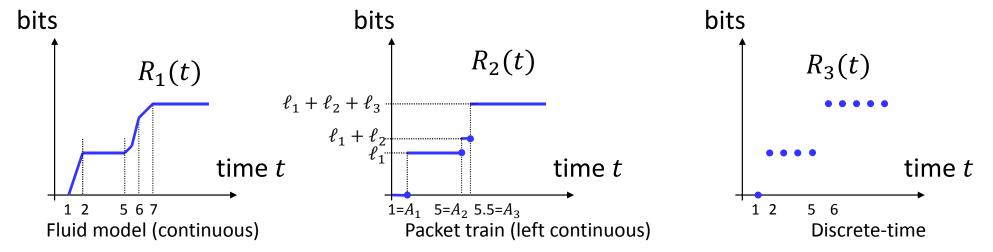
For deterministic networking, per-flow and per-class queuing

Derive system equations ⇒ formal proofs

Stochastic extensions exist (not discussed here)

1. Representation of Data Flow

Cumulative flow: R(t), non-decreasing with R(0) = 0

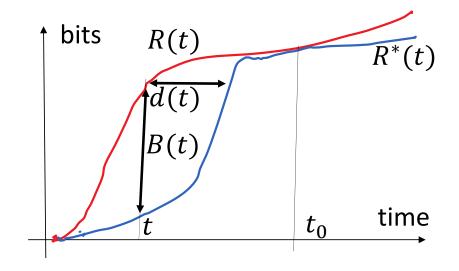


Daters: (A, L) with $A = (A_1, A_2, ...)$ (dates) and $\ell = (\ell_1, \ell_2, ...)$ (lengths in bits)

For a packet train: $R(t) = \sum_{n \ge 1} \ell_n 1_{\{A_n < t\}}$

Delay and Backlog





Backlog at time $t = R(t) - R^*(t)$

If System preserves order for this flow: Delay $\leq h(R,R^*)$ with $h(R,R^*) = \sup_t d(t)$ and $d(t) = \inf\{d \text{ s. t. } R(t) \leq R^*(t+d)\}$ (horizontal deviation)

2. Arrival Curve

Flow with cumulative function R(t) has α as (maximal) arrival curve if $R(t) - R(s) \le \alpha(t - s)$ for any $t \ge s \ge 0$

where α is a monotonic nondecreasing function $\mathbb{R}^+ \to [0, +\infty]$

token bucket constraint (r, b)

(leaky buket constraint)

with rate r and burst b:

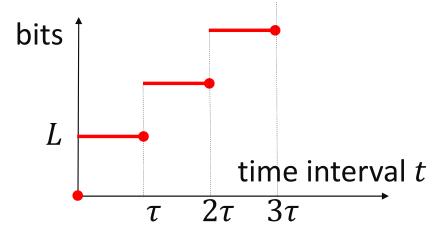
$$\alpha(t) = rt + b$$



[R. Cruz, PhD Dissertation 1987]

periodic stream of packets of size

$$\leq L$$
: $\alpha(t) = L\left[\frac{t}{\tau}\right]$



Aggregation Property

If every flow f has arrival curve α_f then the aggregation $R = \sum_f R_f$ has arrival curve $\sum_f \alpha_f$

If every flow f is token-bucket constrained (r_f, b_f) then the aggregation is token-bucket constrained $(\sum_f r_f, \sum_f b_f)$

Min-Plus Convolution of $f_1, f_2 \ge 0$

$$f(t) = \inf_{s \ge 0} \left(f_1(s) + f_2(t - s) \right)$$

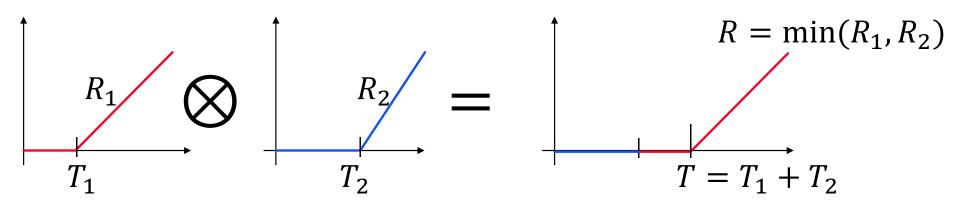
$$f = f_1 \otimes f_2$$

This operation is called *min-plus convolution*. It has the same nice properties as usual convolution; e.g.

$$(f_1 \otimes f_2) \otimes f_3 = f_1 \otimes (f_2 \otimes f_3)$$

$$f_1 \otimes f_2 = f_2 \otimes f_1$$

It can be computed easily: e.g.



Min-Plus Calculus

 \otimes is associative, commutative

Neutral element: $f \otimes \delta_0 = f$ where $\delta_0(0) = 0$, $\delta_0(t) = +\infty$, t > 0

- \otimes distributes w.r.t. min: $f \otimes (g \wedge h) = (f \otimes g) \wedge (f \otimes h)$
- \otimes is isotone: $f \leq f'$ and $g \leq g' \Rightarrow f \otimes g \leq f' \otimes g'$

Functions passing through the origin (f(0) = g(0) = 0):

$$f \otimes g \leq f \wedge g$$

Concave functions passing through the origin: $f \otimes g = f \wedge g$ Convex piecewise linear functions: $f \otimes g$ is the convex piecewise linear function obtained by putting end-to-end all linear pieces of fand g, sorted by increasing slopes

[Bouillard et al 2018, Chapters 3 and 4]

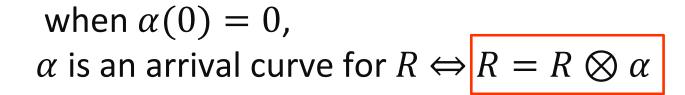
Min-Plus Convolution and Arrival Curves

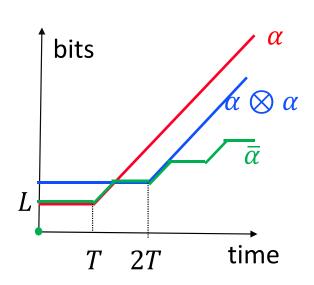
$$\alpha$$
 is an arrival curve for $R \Leftrightarrow R(t) \leq R(s) + \alpha(t-s), \forall s \in [0,t]$
 $\Leftrightarrow R \leq R \otimes \alpha$

Any arrival curve α can be replaced by its sub-additive closure

$$\bar{\alpha} = \inf \{ \delta_0, \alpha, \ \alpha \otimes \alpha, \ \alpha \otimes \alpha \otimes \alpha, \dots \}$$
 with $\delta_0(0) = 0$, $\delta_0(t) = +\infty$ for $t > 0$

 $\bar{\alpha}$ is sub-additive, i.e. $\bar{\alpha}(s+t) \leq \bar{\alpha}(s) + \bar{\alpha}(t)$ and $\bar{\alpha}(0) = 0$



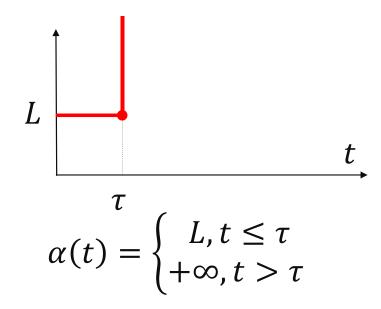


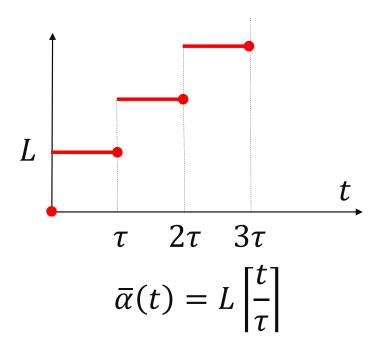
Example of Sub-Additive Closure

Flow has at most L bits in any interval of duration τ

$$\Leftrightarrow R(t+\tau) - R(t) \le L \text{ for all } t$$

- \Leftrightarrow flow has arrival curve α
- \Leftrightarrow flow has arrival curve $\bar{\alpha}$





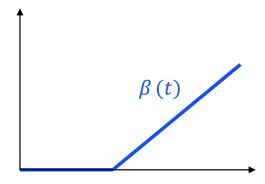
3. Service Curve

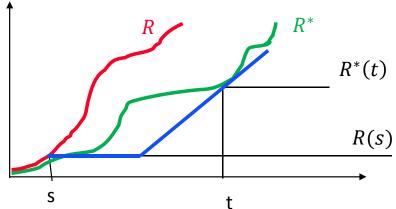


System offers to this flow a (minimal) service curve β if $R^* \geq R \otimes \beta$, i.e. :

$$\forall t \ge 0, \exists s \in [0, t]: R^*(t) \ge R(s) + \beta(t - s)$$

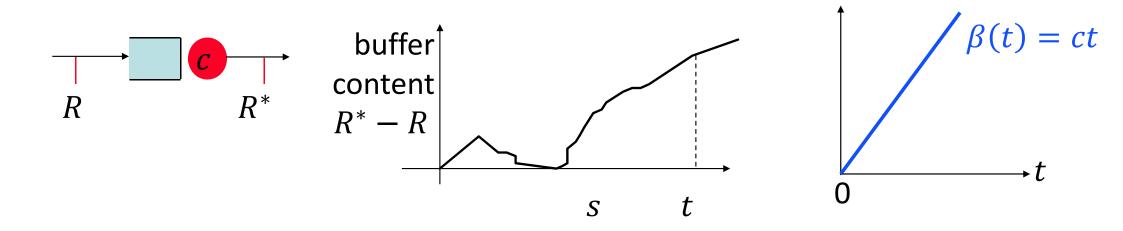
where β is a function : $\mathbb{R}^+ \to \mathbb{R} \cup \{+\infty\}$





[Le Boudec 96, Chang 97, Bouillard et al 2018]

The constant rate server offers service curve $\beta(t) = ct$



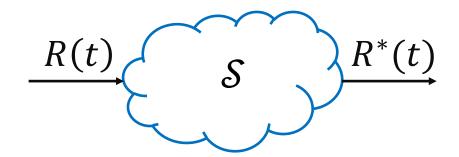
Proof: take s = beginning of busy period:

$$R^*(t)-R^*(s) = c (t-s) \text{ and } R^*(s) = R(s)$$

$$\Rightarrow R^*(t)-R(s) = c (t-s)$$

 $\beta(t) = ct$ is a service curve; it is also a *strict* service curve [Cruz 95]

Strict Service Curve

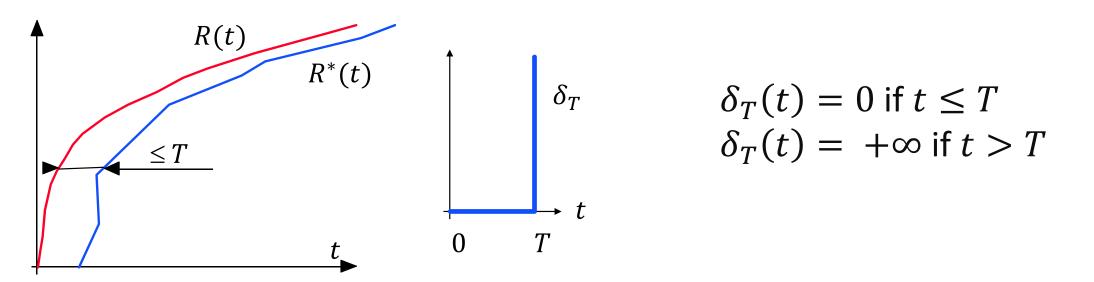


System S offers to a flow a strict service curve β if for any s < t inside a backlogged period, i.e. such that $R^*(u) < R(u), \forall u \in (s, t]$, we have $R^*(t) - R^*(s) \ge \beta(t - s)$

 \mathcal{S} is typically a single queuing point

strict service curve ⇒ service curve

The guaranteed-delay node offers service curve δ_T



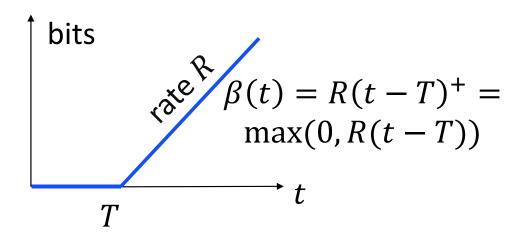
For a node that is FIFO for this flow:

delay $\leq T \iff$ nodes offers to this flow a service curve δ_T

Service Curve Examples

Rate-latency service curve:

$$\beta(t) = R(t - T)^+$$



Example: Static Priority without pre-emption, fixed line rate C

High prio:
$$\beta_H(t) = (Ct - MTU_L)^+$$

(strict service curve) ($MTU_L = \max \text{ packet size, low prio}$)

Low prio: when high priority constrained by $\alpha(t) = rt + b$, r < C:

$$\beta_L(t) = ((C - r)t - b)^+$$
 (not a strict service curve)

$$\beta'_{L}(t) = ((C - r)t - b - MTU_{L})^{+}$$
 (strict service curve)

[Bouillard et al 2018]

Service Curve Example: Deficit Round Robin

Popular per-flow scheduler, one queue per flow [Shreedhar and Varghese, 1995] Visit every queue in sequence and at every visit, serve up to Q_i bits.

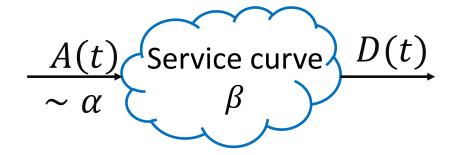
DRR offers to flow i a strict service curve:

$$\beta_i(t) = R_i(t - T_i)^+$$
 with $R_i = \frac{Q_i}{\sum_j Q_j} c$, $T_i = \frac{\overline{Q}_i + \overline{L}_i}{c} + L_{\max,i}(\frac{1}{R_i} - \frac{1}{c})$, $\overline{Q}_i = \sum_{j \neq i} Q_j$, $\overline{L}_i = \sum_{j \neq i} L_{\max,j}$ and c is the line rate.

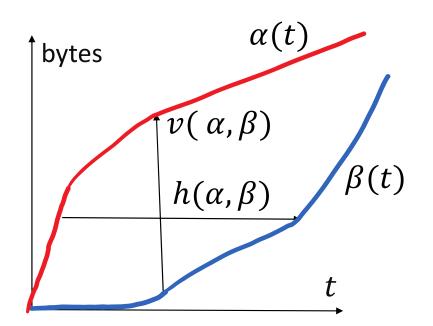
[Boyer et al 2012]

 Other examples: Packetized Generalized Processor Sharing, RFC 2212, IEEE AVB, IEEE TSN, etc. [De Azua – Boyer 2014] [Bouillard et al 2018]

Three Tight Bounds

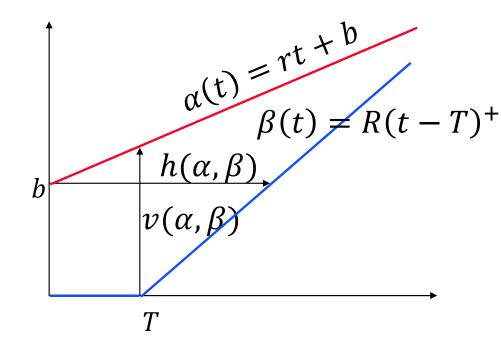


Flow is constrained by arrival curve α ; served in network element with service curve β . Then



- 1. $\operatorname{backlog} \leq v(\alpha, \beta) = \sup_{t} (\alpha(t) \beta(t))$
- 2. if FIFO for this flow, delay $\leq h(\alpha, \beta)$
- 3. output is constrained by arrival curve $\alpha^*(t) = \sup_{u \ge 0} (\alpha(t+u) \beta(u))$ i.e. $\alpha^* = \alpha \oslash \beta$ (deconvolution)

Example



One flow, constrained by one token bucket is served in a network element that offers a rate latency service curve Assume $r \leq R$

Backlog bound: b + rT

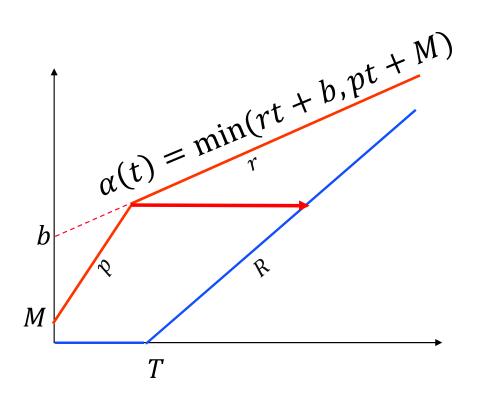
Delay bound: $\frac{b}{R} + T$

Output arrival curve:

$$\alpha^*(t) = rt + b^*$$

with $b^* = b + rT$

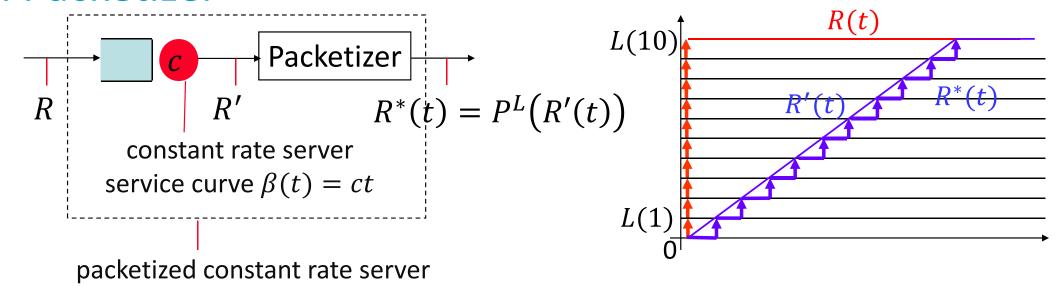
Example with peak rate limit



Assume $r \leq R$

Delay bound:
$$\frac{M + \frac{b - M}{p - r}(p - R)^{+}}{R} + T$$

4. Packetizer



Packetization is captured by the function P^L : [Chang-Lin 1998]

$$P^{L}(x) = L(n) \Leftrightarrow L(n) \leq x < L(n+1)$$

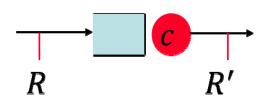
with
$$L(n) = \ell_1 + \ell_2 + \dots + \ell_n$$

Packetizer is the system $R \to P^L(R)$

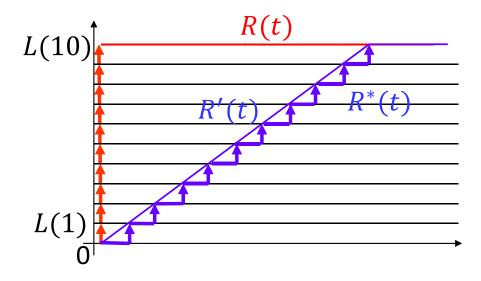
service curve $\beta(t) = ct + \ell^{max}$

Service Curve Definition Must Specify Packetization or

Not

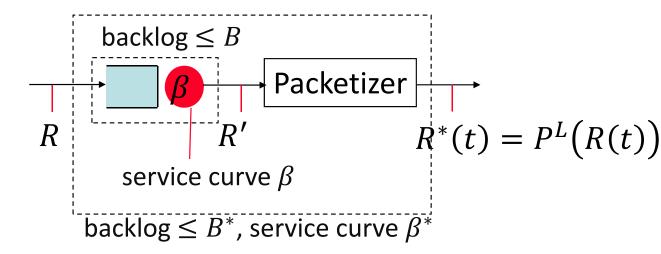


This system offers the service curve $\beta(t) = ct$



If we consider only emission times of entire packets, (i.e. the output is R^*), the system now offers the (weaker) service curve $\beta(t) = (ct - \ell^{max})^+$

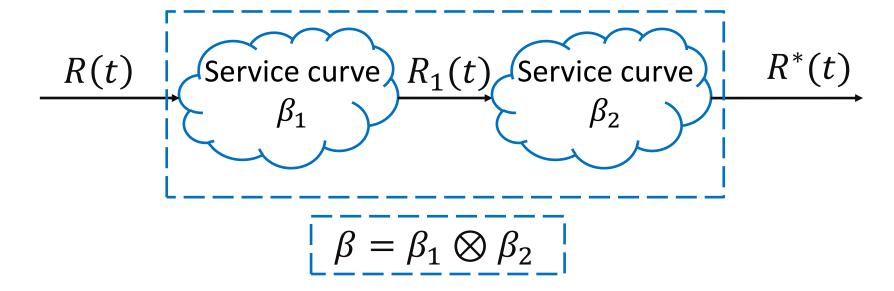
Effect of Packetization



- 1. Delay bounds are same for R' and R^*
- 2. Backlog bound $B^* = B + \ell^{max}$
- 3. Service curve $\beta^*(t) = [\beta(t) \ell^{max}]^+$
- 4. If a fluid flow R(t) has arrival curve $\alpha(t)$ then the packetized flow $P^L(R(t))$ has arrival curve $\alpha(t) + \ell^{max}$

$$\ell^{max} = \max_n \ell_n$$

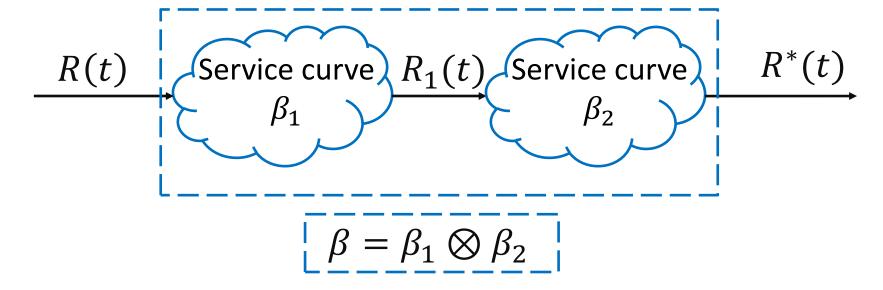
5. Concatenation



A flow is served in series, network element i offers service curve β_i . The concatenation offers to flow the service curve $\beta=\beta_1\otimes\beta_2$

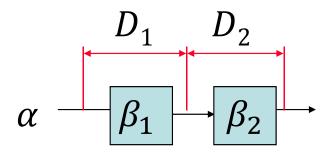
Proof: $R^* \ge R_1 \otimes \beta_2 \ge (R \otimes \beta_1) \otimes \beta_2 = R \otimes (\beta_1 \otimes \beta_2)$

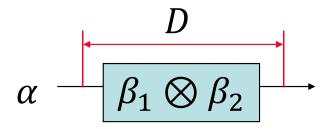
Example



If β_i is rate-latency R_i , T_i then the concatenation β is rate-latency $R = \min(R_1, R_2)$ and $T = T_1 + T_2$

Pay Bursts Only Once





$$\alpha(t) = rt + b$$

$$\beta_1(t) = R(t - T_1)^+$$

$$\beta_2(t) = R(t - T_2)^+$$

$$r \le R$$

one flow constrained at source by α end-to-end delay bound computed node-by-node (also accounting for increased burstiness at node 2):

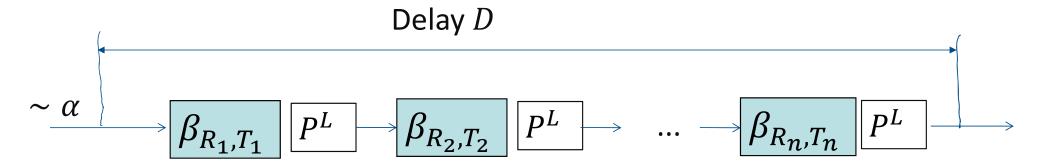
$$D_1 + D_2 = \frac{2b + rT_1}{R} + T_1 + T_2$$

computed by concatenation:

$$D = \frac{b}{R} + T_1 + T_2$$

i.e. worst cases cannot happen simultaneously – concatenation captures this!

Packetization and Concatenation



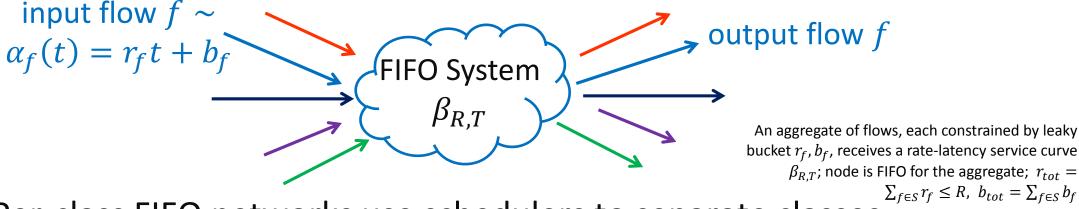
To compute delay bound D, use end-to-end service curve ignoring last packetizer

$$D \leq h(\alpha, \beta_{R,T})$$

with
$$R = \min_{i=1...n} R_i$$
 and $T = \sum_{i=1}^n T_i + (n-1)R_i\ell^{max}$

Cannot ignore the intermediate packetizers.

6. Per-Class FIFO Networks



Per-class FIFO networks use schedulers to separate classes Service received by a class can be modelled by a rate-latency service curve $\beta_{R,T}$ (e.g. : DRR, AVB, TSN) [Boyer et al 2012, De Azua – Boyer 2014].

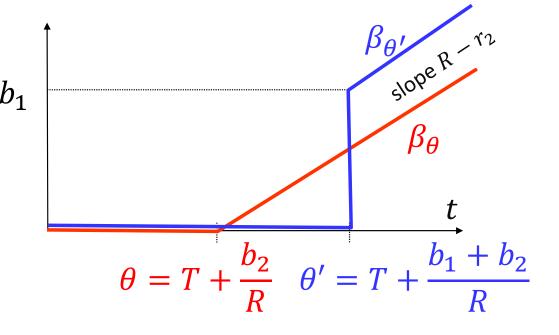
delay bound for any packet of any flow: $D = \frac{b_{tot}}{R} + T$ backlog bound for the aggregate of all flows: $B = b_{tot} + r_{tot}T$

[Le Boudec-Thiran 2001, Section 6.4] [Bouillard et al 2018, Chapters 10,11]

FIFO Residual Service Curve

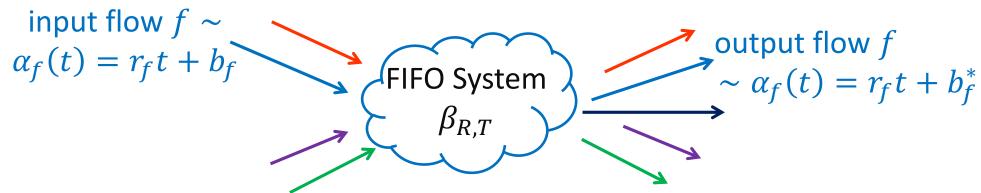
Flows 1 and 2 served FIFO + service α_2 curve β to the aggregate; Flow 2 is constrained by arrival curve α_2 \Rightarrow for every θ , β_{θ} is a service curve for flow 1, with $\beta_{\theta}(t) = [\beta(t) - \alpha_2(t - \theta)]^+ 1_{\{t > \theta\}}$

Example: $\alpha_i(t) = r_i t + b_i$, $\beta = \text{rate-latency}(R, T)$ β_{θ} and β_{θ} , are service curves for flow 1



FIFO System

Analyzing Per-Class Networks



arrival curve for output f is leaky bucket r_f , b_f^* with

$$b_f^* = b_f + r_f \left(T + \frac{b_{tot} - b_f}{R} \right)$$

(obtained using service curve β_{θ} with $\theta = T + \frac{b_{tot} - b_f}{R}$)

Burstiness of every flow inside network increases along its path as a function of other flows' burstiness (cascade).

Solved recursively in feed-forward networks, otherwise by fix-point.

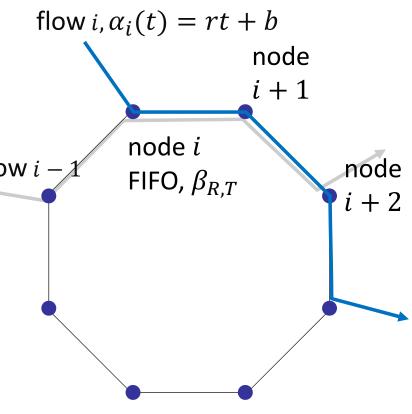
Example

 b_j = burstiness of every flow i after j hops, with $b_0 = b$ and :

$$b_{j} = b_{j-1} + r \left(T + \frac{b_{tot} - b_{j-1}}{R} \right)$$

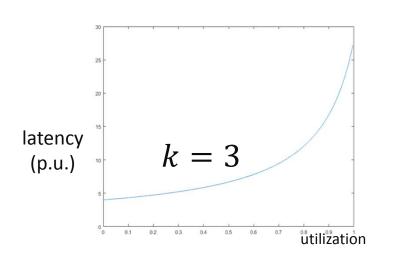
$$b_{tot} = b + b_{1} + \dots + b_{k-1}$$
flow $i - 1$

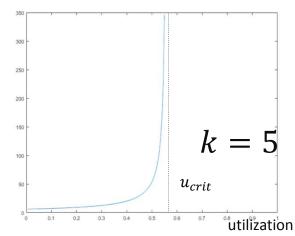
Fixed point in $(b_{tot}, b_1, ..., b_{k-1})$ has a positive solution when $(k-1)r + (1-r)^k < 1$, which occurs for $r < r_{crit}$

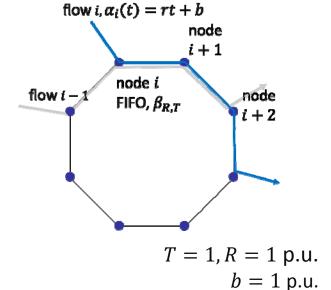


one flow sourced at every node, uses k hops k=3 on the figure all flows have same arrival curve at source I nodes, I flows in total kr < R

Upper Bound on Latency at any Node





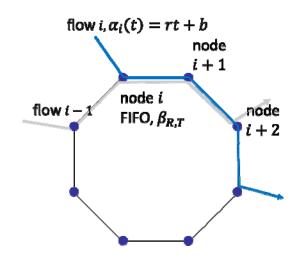


k	1	2	3	4	5	6	7	8
$u_{crit} = k r_{crit}$	1	1	1	0.7579	0.5591	0.4409	0.3632	0.3084

If positive fixed point exists, then it gives a valid bound (time-stopping method)

Delay Based Method

If a system imposes a delay $\leq D$ to a flow f with input arrival curve α_f , an output arrival curve is $\alpha_f(t+D)$.



Often used in feed-forward networks [Boyer et al 2011]

For this ring example: after j hops, delay $\leq jD$, hence the fix-point:

$$b_j = b + jrD$$
, $D = \frac{b + b_1 + \dots + b_{k-1}}{R} + T$

Delay bound and $u_{crit} = \min\left(1, \frac{2}{k-1}\right)$ are less good than with previous method.

Other Methods

Several techniques improve delay bounds, tightness and u_{crit} : PMOO, PMOC, linear programming, etc.

[Bouillard et al 2018][Amari et al 2016] [Boyer et al 2012] [Bouillard-Stea 2015][Bondorf et al 2017] [Rizzo-Le Boudec 2008] [Tassiulas-Georgiadis 1996] [Chlamtac et al 1998]

There cannot be a bound that depends only on max aggregate burstiness, number of hops h and link utilization u when $u \ge \frac{1}{h-1}$

[Charny – Le Boudec 2000]

Stability of a FIFO Network

Every flow $f \in \mathcal{F}$ constrained by $\alpha_f(t) = r_f t + b_f$ at source. Route of flow f is fixed. $F_i \subset \mathcal{F}$ is the set of flows passing through node i.

Every node $i \in \mathcal{I}$ is FIFO and offers to the aggregate of flows $f \in \mathcal{F}_i$ a rate-

latency service curve
$$\beta_{R_i,T_i}$$
. Load factor $u = \max_i \left(\frac{\sum_{f \in F_i} r_f}{R_i}\right)$. \mathcal{F} , \mathcal{I} finite.

Network underloaded: u < 1; overloaded: u > 1; critical: u = 1;

One network instance = $(\mathcal{F}, r, b, F, \mathcal{I}, R, T)$

A network instance is stable if there is a bound on all delays (or backlogs), that is valid for any execution trace of the network.

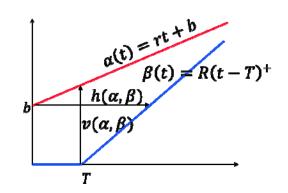
(existence of a bound on all delays ⇔ existence of a bound on all backlogs)

Which FIFO Networks are Stable?

An overloaded FIFO network is not stable.

A single-node network that is underloaded or critical is stable.

A feed-forward network that is underloaded or critical is stable.



Question: Is an arbitrary underloaded network stable?

Is an Arbitrary Underloaded FIFO Network Stable?

For any $\varepsilon>0$ there is an unstable underloaded FIFO network with load factor $u<\varepsilon$ [Andrews 2009]

Every underloaded ring is stable [Tassiulas and Georgiadis 1996, Le Boudec and Thiran 2001]

If the interference condition [(4) in Rizzo-Le Boudec 2007] holds and service curves are strict then the FIFO network is stable; in the special case $R_i = R$, $\forall i$, the condition is $r_f \leq R/(1 + RIN_f)$ where RIN_f is the number of flows that interfere with f.

7. Fluid Shapers

fresh traffic
$$R$$
 shaped traffic R' α -smooth

(Fluid) Shaper forces output to be constrained by α (Fluid) Greedy Shaper stores data in a buffer only if needed Examples:

constant bit rate link is fluid greedy shaper for $\alpha(t) = ct$

Shaper constraints are

$$R'(t) \le R(t)$$

 $R'(t) \le (R' \otimes \alpha)(t)$

Min-Plus Residuation Theory [Baccelli et al. 1992]

 \mathcal{G} is the set of wide-sense increasing functions $[0, +\infty) \to [0, +\infty]$ and $\Pi: \mathcal{G} \to \mathcal{G}$. Consider the set of functions $x \in \mathcal{G}$ that satisfy

(P)
$$x(t) \le [\Pi(x)](t)$$
 and $x(t) \le g(t)$ for some $g \in \mathcal{G}$

If Π is isotone and upper-semi-continuous, there is one maximal solution to (P). It is given by

$$x^* = \inf\{x^0, x^1, x^2, ...\}$$
 with $x^0 = g$ and $x^{i+1} = \Pi(x^i)$.

" Π isotone" means that $x \le y \Rightarrow \Pi(x) \le \Pi(y)$; " Π upper semi-continuous" means that $\Pi\left(\inf_n x_n\right) = \inf_n \Pi(x_n)$

I/O Characterization of Fluid Greedy Shaper

The problem optimal shaper (where the unknown is the function R') $R'(t) \leq R(t)$ $R'(t) \leq (R' \otimes \alpha)(t)$

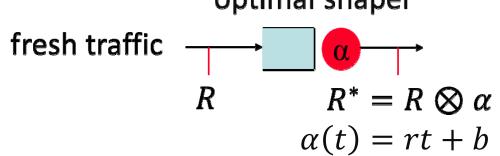
has one maximal solution R^* , given by $R^* = R \otimes \bar{\alpha}$

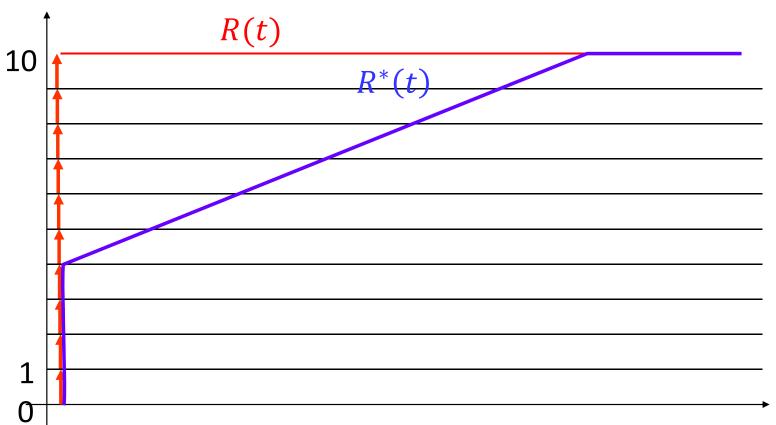
We can always assume that α is sub-additive and $\alpha(0)=0$ so that $R^*=R\otimes\alpha$

 \Rightarrow greedy shaper has service curve α

Example

optimal shaper





$$b = 4 p.u.$$

Fluid Greedy Shaper Keeps Arrival Constraints

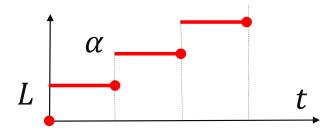
fresh traffic constrained by α R^* re-shaped traffic

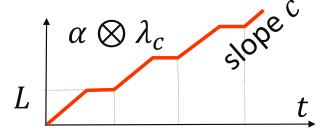
The output of the fluid greedy shaper is still constrained by α **Proof:**

$$R^* = R \otimes \sigma = (R \otimes \alpha) \otimes \sigma = (R \otimes \sigma) \otimes \alpha = R^* \otimes \alpha$$

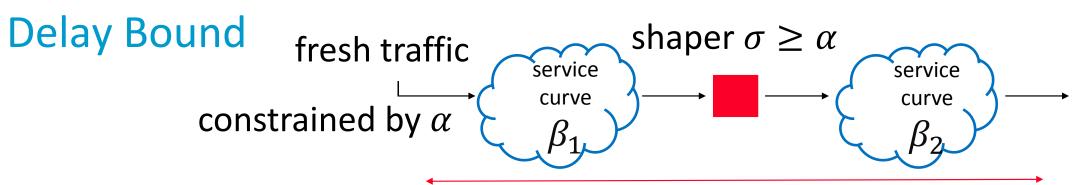
Application: if flow, with arrival curve α , is transmitted over a constant rate line of rate c, the output has arrival curve $\alpha \otimes \lambda_c$

$$(\lambda_c(t) = ct)$$





Fluid Greedy Shapers Do Not Increase End-to-end



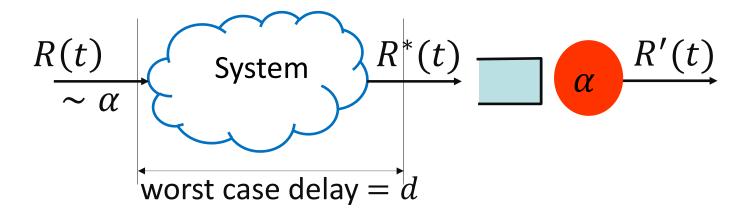
same end-to-end delay bound with or without shaper

Proof:
$$h(\alpha, \beta_1 \otimes \sigma \otimes \beta_2) = h(\alpha, \sigma \otimes \beta_1 \otimes \beta_2) = h(\alpha, \beta_1 \otimes \beta_2)$$

Re-shaping traffic is for free (in terms of delay), but reduces downstream buffering.

Fluid Greedy Re-Shaper does not Increase Worst-Case

Delay



If R has arrival curve α and if $h(R, R^*) \leq d$ then $h(R, R') \leq d$.

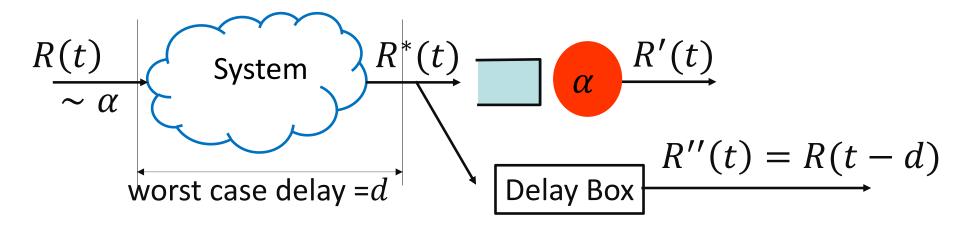
Proof: Note that $h(R, R^*) \leq d \Leftrightarrow R^* \geq R \otimes \delta_d$

By hypothesis: $R = R \otimes \alpha$ and $R^* \geq R \otimes \delta_d$

Now $R' = R^* \otimes \alpha$

$$\Rightarrow R' \geq (R \otimes \delta_d) \otimes \alpha = (R \otimes \alpha) \otimes \delta_d = R \otimes \delta_d$$

An Alternative Proof



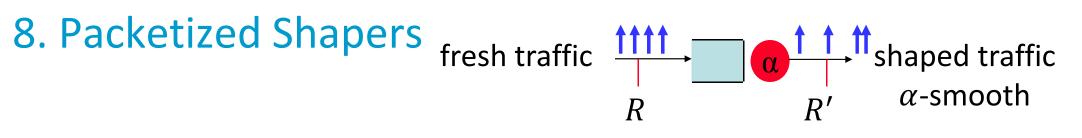
If R has arrival curve α and if $h(R, R^*) \leq d$ then $h(R, R') \leq d$.

Proof: Note that $h(R, R^*) \le d \Leftrightarrow R^*(t) \ge R(t - d)$

The delay box is a (non-greedy) shaper for R^* ;

therefore (optimality of greedy shaper):

$$R''(t) \le R'(t)$$
 i.e. $R'(t) \ge R(t-d)$

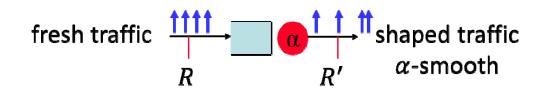


(Packetized) Shaper

forces output to be packetized and constrained by α

(Packetized) Greedy Shaper stores packets in a buffer only if needed

Packetized Shaper



Packetized Shaper constraints are

$$R'(t) \le R(t)$$

$$R'(t) \le (R' \otimes \alpha)(t)$$

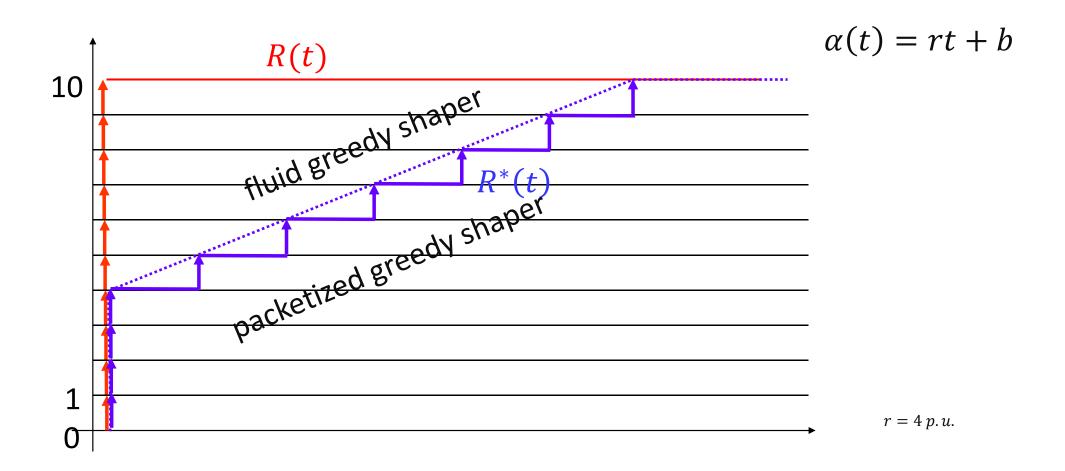
$$R'(t) \le P^{L}(R'(t))$$

There is a maximal solution (Packetized Greedy Shaper)

$$R^*=\inf\{R^{(1)},R^{(2)},\dots\}$$
 with $R^{(0)}=R$ and $R^{(i)}=P^L\big(\alpha\otimes R^{(i-1)}\big)$

Example

fresh traffic
$$R^*$$
 shaped traffic R^* α -smooth

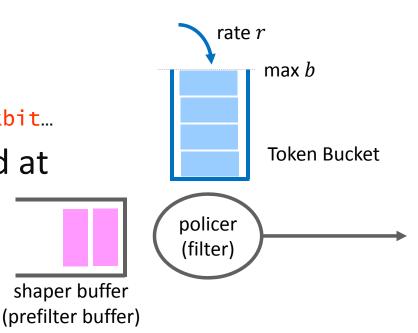


Linux's Token Bucket Filter (r, b)

tc qdisc add dev eth0 root tbf rate 1mbit burst 32kbit...

Token bucket is spontaneously replenished at rate r up to some maximum b.

In order to be released, a packet must consume an amount of tokens equal to its size.



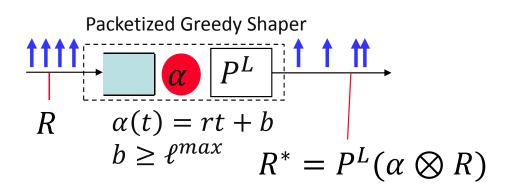
If there are not enough tokens, packet must wait. As soon as there are enough tokens, packet is released.

TBF(r, b) is the packetized greedy shaper for the arrival curve $\alpha(t) = rt + b$.

Packetized Greedy Shaper

When

(C) α is piecewise-linear, concave and $\alpha(0^+) \ge \ell^{max}$



then $R^* = P^L(\alpha \otimes R)$ i.e. packetized greedy shaper = fluid greedy shaper + packetizer.

This is why TBF(r, b) = packetized greedy shaper for $\alpha(t) = rt + b$. Such packetized greedy shapers keep arrival constraints.

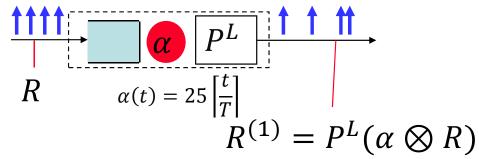
[Le Boudec 2002]

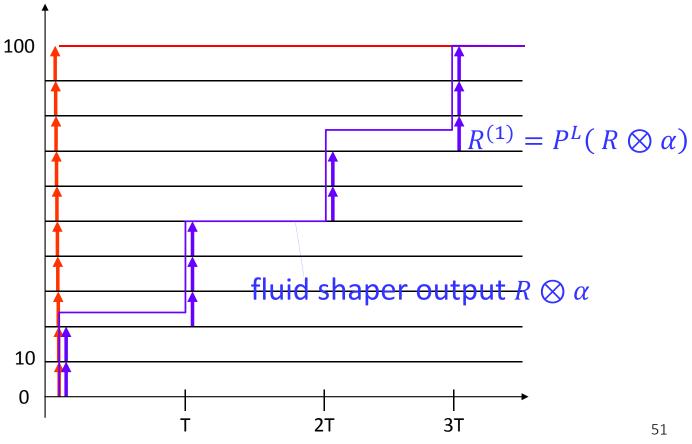
Counter-Example

$$\alpha(t) = 25 \left[\frac{t}{T} \right]$$

(at most 25 data units every T time units)

R(t) = 10 packets of size 10 at time t=0 $R^{(1)} = \alpha \otimes R$ is not constrained by arrival curve α

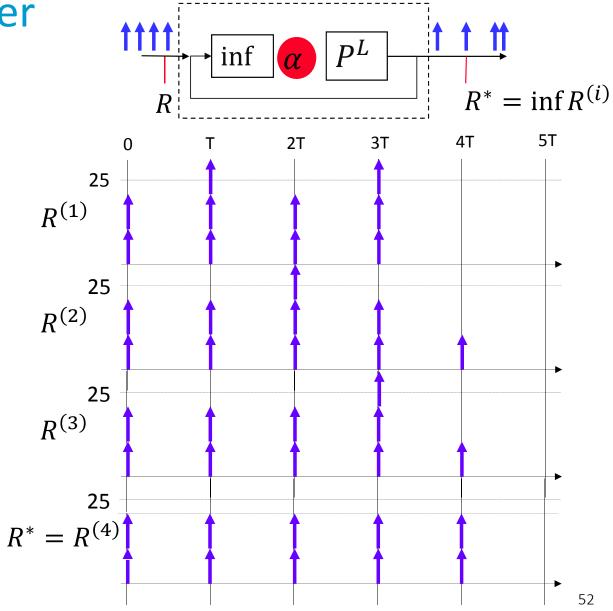




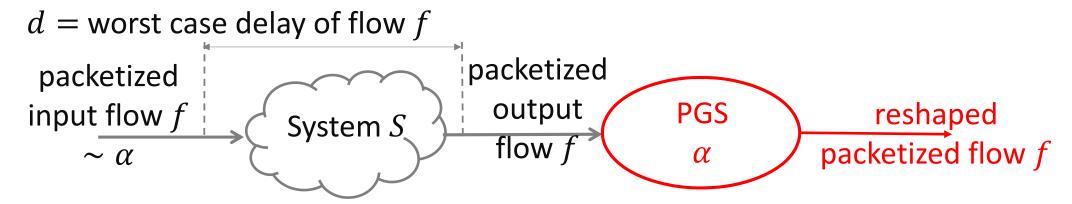
Packetized Greedy Shaper Output

When (C) does not hold (e.g. for staircase arrival curves), $R^* \neq P^L(\alpha \otimes R)$ the iteration does not stop at step 1

(and packetized greedy shaper may not keep arrival constraints)



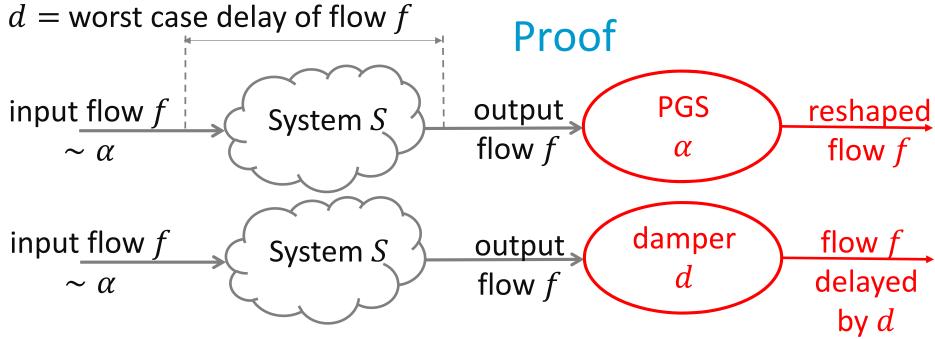
Delay Property of Packetized Greedy Shapers



One packetized flow f goes through a system S; system S is FIFO for flow f; flow f is constrained by arrival curve α at input to S; output flow f is reshaped at output through a packetized greedy shaper for same arrival curve α (shaper is FIFO)

Theorem: The worst case delay of flow f is not increased:

Re-shaping is for free! [Le Boudec 2018] -- True whether (C) holds or not.

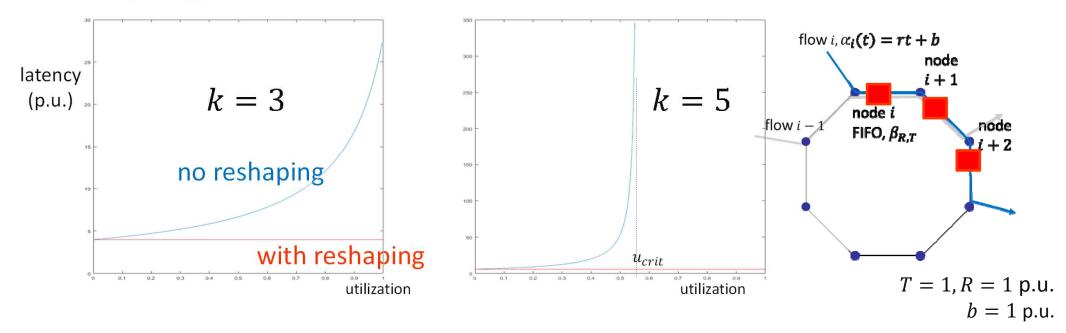


Replace packetized greedy shaper by damper [Verma et al 1991]:

Damper forces total delay of flow f to be exactly d; Damper is causal if d is \geq worst-case delay through S.

Output of damper is input flow f, time-shifted by $d\Rightarrow$ is α —smooth \Rightarrow Damper is a packetized shaper \Rightarrow (maximal property of packetized greedy shaper) flow f delayed by d is no earlier than reshaped flow f

Re-Shaping Avoids Issue of Non-Feedforward Networks

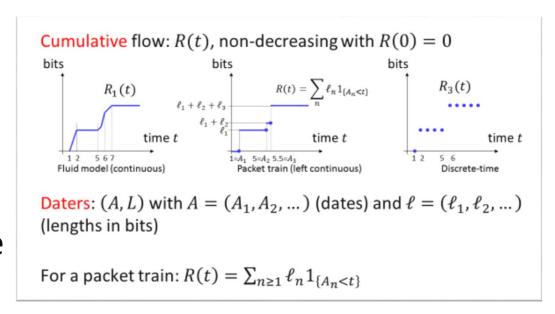


Per-flow (re-) shaper at every node (e.-g. TBF) avoids burstiness cascade

Implementation requires per-flow FIFO ⇒ see Interleaved Regulator for a solution [Le Boudec 2018]

9. Min-Plus or Max-Plus?

Network calculus uses mainly cumulative arrival or departure functions (R(t) = number of bits observed in t time units) \rightarrow min-plus algebra

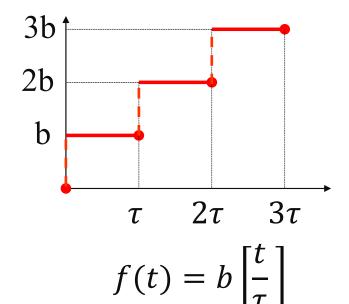


Liebeherr uses cumulative arrival time functions (T(x) = time) taken to observe x bits); leads to a dual, quasi-equivalent approach, that uses max-plus algebra. Duality uses pseudo-inverses $R = T^{\downarrow}$, $T = R^{\uparrow}$. [Liebeherr 2017]

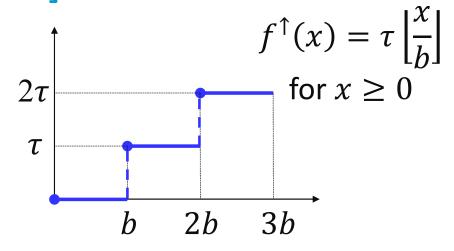
Pseudo-Inverses [Liebeherr 2017]

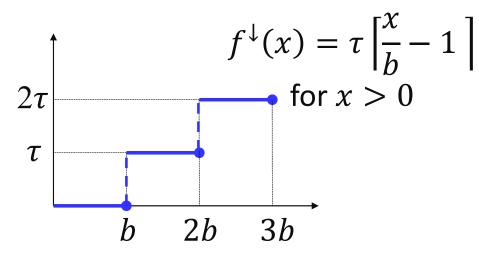
$$f^{\downarrow}(x) = \inf \{t, f(t) \ge x\}$$

$$f^{\uparrow}(x) = \sup\{t, f(x) \le x\}$$



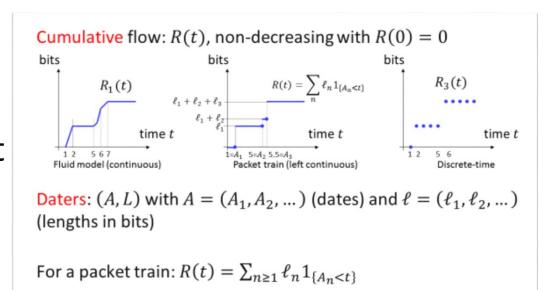






Chang's Max-Plus Calculus

Yet a different approach, uses
Daters (also called "Marked Point
Process"). Leads to a different
max-plus algebra where
"convolution" is



$$(A \odot_L g)(x) = \max_{1 \le m \le n} (A_m + g(\ell_m + \ldots + \ell_{n-1}))$$

[Chang 2002]

Not associative nor commutative

E.g. A flow is g —regular if $A \ge A \odot_L g$

E.g.
$$g(x) = \frac{x}{r}$$
, flow is g —regular $\Leftrightarrow A_n - A_{n-1} \ge \frac{\ell_{n-1}}{r}$ called LRQ-rule in [Specht-Samii 2016]

Chang's g-regularity

g-regularity is an alternative to arrival curve, but is not equivalent. Does not work well with aggregation.

g-regularity can be mapped approximately to arrival curve: e.g.

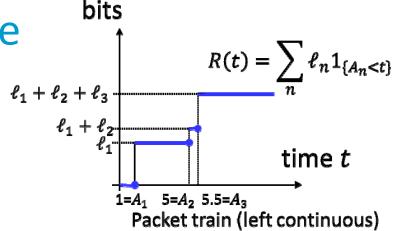
$$g$$
 —regular with $g(\ell) = \frac{\ell}{r} \Rightarrow$ arrival curve $\alpha(t) = rt + \ell^{MAX}$

arrival curve
$$\alpha(t) = rt + \ell^{MAX} \Rightarrow g$$
 —regular with $g(\ell) = \frac{(\ell - \ell^{MAX})^{T}}{r}$ $\ell^{MAX} = \max packet size$

Instead, we discuss next the use of Daters / Max-Plus with standard network calculus concepts of arrival curves (in the future, with service curves).

Max-Plus Expression of Arrival Curve

Theorem: Arrival curve constraint α is equivalent to



$$A_n - A_m \ge \alpha^{\downarrow}(\ell_m + \dots + \ell_n)$$
 for all $1 \le m \le n$

[Le Boudec 2018]

E.g. for
$$\alpha(t) = rt + b$$
, $\alpha^{\downarrow}(x) = \max(0, \frac{x-b}{r})$

Equivalent Formulations

	Original Definition	Equivalent Max-Plus Formulation
affine arrival curve	R(t) - R(s)	$A_n - A_m$
(leaky bucket)	$\leq r(t-s)+b$	$A_n - A_m$ $\geq \frac{L_m + \dots + L_n - b}{r}$
staircase arrival curve (at most b bits in τ seconds)	$R(t) - R(s) \le b \left[\frac{t}{\tau} \right]$	$A_n - A_m$ $\geq \tau \left[\frac{L_m + \dots + L_n - b}{b} \right]$

 $R(t) = \text{number of bits seen in } [0, t]; A_m = \text{arrival time for packet } n$

Max-Plus Representation of Rate-Latency Service Curve

A FIFO network element offers a rate-latency service curve $\beta_{R,T}$



Input flow is packetized

Then: for every n there exists some $m \leq n$ s.t.

$$D_n \le A_m + \frac{\ell_m + \dots + \ell_n}{R} + T$$

And conversely, if this holds for some network element S, then S is the concatenation of a rate-latency service curve element and a packetizer (= Guaranteed Rate node)

Max-Plus Representation of Packetized Greedy Shaper

$$A_n \xrightarrow{\uparrow \uparrow \uparrow \uparrow} D_n^*$$

$$R^*(t) = \sum_n \ell_n 1_{\{D_n^* < t\}} = \inf_i R^{(i)}(t),$$

$$R^{(0)} = R, \quad R^{(i)} = P^L(R^{(i-1)} \otimes \alpha)$$
reedy Shaper α

Packetized Greedy Shaper α

The output times D_n^* of packetized greedy shaper are given by $D_1^* = A_1$ and

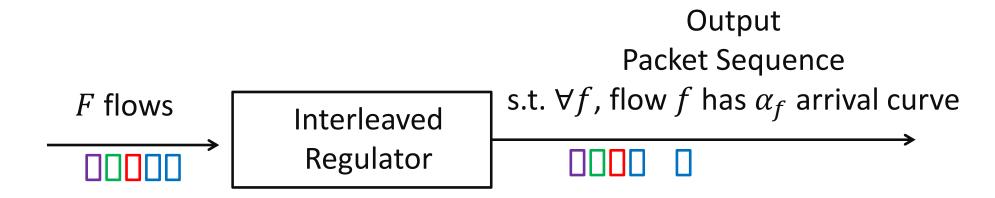
$$D_n^* = D_{n-1}^* \vee A_n \vee \bigvee_{m=1}^{n-1} \left(A_m + \alpha^{\downarrow} (\ell_m + \dots + \ell_n) \right)$$

(time domain representation of PGS)

[Le Boudec 2018]

(optimality) For any other (non greedy) packetized shaper, the output times D'_n satisfy $D'_n \geq D^*_n$

Application: Interleaved Regulator



An Interleaved Regulator (= interleaved packetized shaper) is a system such that is globally FIFO + every output flow f has α_f arrival curve.

Theorem: there is one minimal interleaved regulator, i.e. one that ouput packets no later than any other interleaved regulator.

[Le Boudec 2018]

Implementation of Minimal Interleaved Regulator

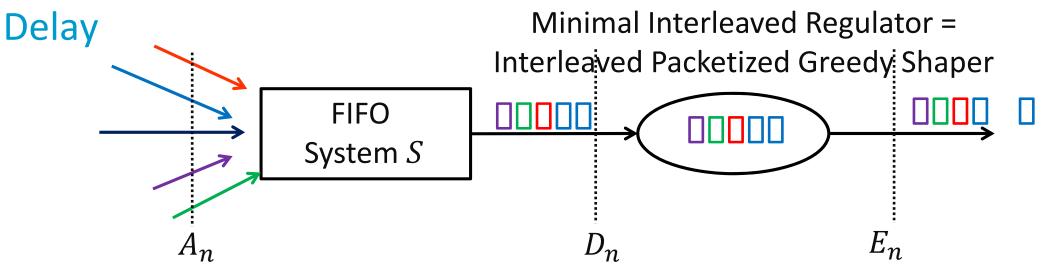
$$D_n = \max\left\{A_n, D_{n-1}, \bigvee_{m=1}^{i-1} \left(A_m^f + \alpha^{\downarrow} (\ell_m^f + \dots + \ell_i^f)\right)\right\}$$
 Eligibility Time of packet at head of queue

with f= flow of packet n, i= index of packet n in its flow, $A_m^f=$ arrival time of mth packet of flow f, $\ell_m^f=$ length of mth packet of flow f

- One FIFO queue for all packets of all flows.
- Packet at head of queue is examined and delayed until it can be released while satisfying the arrival curve of its flow.
- Other packets wait until their turn comes.

[Specht-Samii 2016], called "Urgency Based Scheduler". In IEEE TSN, called "Asynchronous Traffic Shaping".

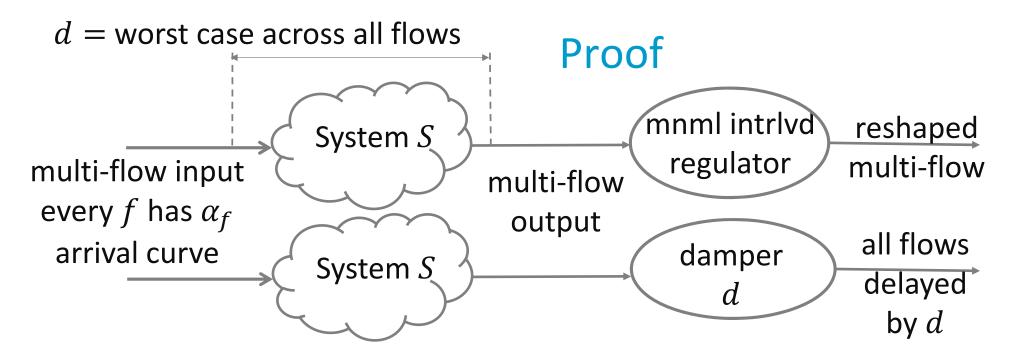
Minimal Interleaved Regulator Does Not Increase Worst Case



Every flow f has α_f arrival curve before input to S Output of S is fed to minimal interleaved regulator with arrival curve α_f for flow f

Theorem:
$$\sup_{n} (D_n - A_n) = \sup_{n} (E_n - A_n)$$

Worst-case delay of S across all flows is not increased by minimal interleaved regulator [Le Boudec 2018] [Le Boudec 2018 – slides]



- Replace minimal regulator by **damper** [Verma et al 1991]: Damper forces total delay of input to be exactly d; Damper is causal if d is \geq worst-case delay through S
- Damper is an interleaved regulator \Rightarrow multi-flow output delayed by d is no earlier than reshaped multi-flow

Other Regulation Constraints

Example: Packet Burstiness $PB(\rho, K)$ defined by:

number of packets seen in interval of duration t is $\leq \rho t + K \Leftrightarrow$

$$A_n - A_m \ge \frac{n - m + 1 - K}{\rho}$$
 for $m \le n$ [Le Boudec 2018, Jiang 2018]

Regulator concept replaces the concept of shaper; under mild conditions (``Pi-regulation"), any regulation rule has a minimal regulator. Any combination of regulation rules has a minimal interleaved regulator.

Minimal regulator does not increase per-flow delay.

Minimal Interleaved regulator does not increase FIFO system delay.

[Le Boudec 2018] [Le Boudec 2018 – slides]

Packet Count, Event Stream

Arrival function R(t) = number of bits up to time tPacket count function P(d) = number of packets in d bits Event count function E(t) = number of packets up to time t E(t) = P(R(t)) (event stream) $P^L(R(t)) = P^{\downarrow}(P(R(t)))$ (packetizer) [Boyer-Roux 2016]

Theorem: The conditions are equivalent

- 1. $E(t) E(s) \le f(t s)$ for any $0 \le s \le t$
- 2. $A_n A_m \ge f^{\downarrow}(n-m+1)$ for all $1 \le m \le n$ where A_n is arrival date of packet n [Le Boudec-slides 2018]

Viewpoint

Cumulative functions and daters / marked point process are complementary viewpoints. One naturally leads to min-plus, the other to max-plus.

We should be opportunistic and use both (and perhaps other) representations.

We should strive for results that are independent of the representation (e.g. delay properties of optimal regulators).

Tools

- The DiscoDNC
 is an academic Java implementation of the network calculus framework. [6]
- The RTC Toolbox is an academic Java/MATLAB implementation of the Real-Time calculus framework, a theory quasi equivalent to network calculus.^[4]
- The CyNC [7] tool is an academic MATLAB/Symulink toolbox, based on top of the RTC Toolbox [8]. The tool was developed in 2004-2008 and it is currently used for teaching at Aalborg university.
- The RTaW-PEGASE is an industrial tool devoted to timing analysis tool of switched Ethernet network (AFDX, industrial and automotive Ethernet), based on network calculus. [8]
- The Network calculus interpreter

 is an on-line (min,+) interpreter.
- The WOPANets
 is an academic tool combining network calculus based analysis and optimization analysis. [9]
- The DelayLyzer is an industrial tool designed to compute bounds for Profinet networks.^[10]
- DEBORAH

 is an academic tool devoted to FIFO networks.

 [11]
- NetCalBounds is an academic tool devoted to blind & FIFO tandem networks. [12][13]
- The Siemens Network Planner (SINETPLAN☑) uses network calculus (among other methods) to help the design of a PROFINET network.^[14]

copied on 2019 Feb 28 from https://en.wikipedia.org/wiki/Network_calculus

Conclusion

Network calculus main concepts:

arrival curve, minimal service curve and universal bounds shapers, concatenation

for packet-based systems and for fluid systems.

Some key results are based on existence of minimal or maximal solutions to functional problems.

Challenges exist for per-class systems.

Fundamental results use min-plus convolution; other techniques (dater-based) can be useful.

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